Data sheet for three-phase Squirrel-Cage-Motors INNOMOTICS



Motor type: 1AV3131A INNOMOTICS GP - 132 S - IM B5 - 2p Offer no. Client order no. Item-No Order no. Consignment no. Project Remarks Safe Area Electrical data -/cosφ ³⁾ U Δ/Υ f Р Р ī М η 3) I_A/I_N M_A/M_N M_K/M_N IE-CL n [V] [Hz] [kW] [hp] [A] [1/min] [Nm] 4/4 3/4 4/4 2/4 I_I/I_N T_I/T_N T_B/T_N 2/4 3/4 **DOL duty (S1)** - 155(F) to 130(B) 400 Δ 50 7.50 13.10 2950 24.5 90.1 91.0 91.0 0.92 0.90 0.84 8.3 3.9 IE3 690 50 7.50 -/-7.60 0.90 0.84 3.9 IE3 2950 24.5 90.1 91.0 91.0 0.92 8.3 1.9 Δ 460 60 8.60 -/-13.00 3550 23.0 90.2 90.8 90.5 0.90 0.84 8.2 3.9 IE3 0.92 2.0 Δ -/-IE3 460 60 7.50 11.50 3560 20.0 90.2 90.4 89.6 0.91 0.88 0.82 9.4 2.2 4.5 IM B5 / IM 3001 FS 132 S UKCA IEC/EN 60034 IEC, DIN, ISO, VDE, EN Environmental conditions: -20 °C - +40 °C / 1000 m Locked rotor time (hot / cold): 9.3 s | 13.6 s Mechanical data 68 / 80 dB(A) 2) 3) Sound level (SPL / SWL) at 50Hz|60Hz 71 / 83 dB(A) 2) 3) Vibration severity grade Α 0.0310 kg m² Thermal class Moment of inertia F Bearing DE | NDE **S**1 6208 2Z C3 6208 2Z C3 Duty type bearing lifetime Direction of rotation bidirectional $L_{10mh}\,F_{Rad\,\,min}$ for coupling operation $50|60Hz^{\,1)}$ 40000 h 32000 h Frame material aluminum Regreasing device Without Net weight of the motor (IM B3) 57 kg Grease nipple Coating (paint finish) Standard paint finish C2 Preloaded bearing DE Color, paint shade RAL7030 Type of bearing Condensate drainage holes Without Motor protection (A) without (Standard) External earthing terminal Without Method of cooling IC411 - self ventilated, surface cooled Terminal box Terminal box position top Max. cross-sectional area 6 mm^2 Material of terminal box Aluminium Cable diameter from ... to ... 11 mm - 21 mm Type of terminal box TB1 H00 2xM32x1,5 Cable entry Contact screw thread Μ4 Cable gland 2 plugs 1) L_{10mh} according to DIN ISO 281 10/2010 3) Value is valid only for DOL operation with motor design IC411 I_A/I_N = locked rotor current / current nominal M_A/M_N = locked rotor torque / torque nominal 2) at rated power / at full load M_K/M_N = break down torque / nominal torque Transmittal, reproduction, dissemination and/or editing of this document as well as utilization of its contents and communication thereof to others without express authorization are prohibited. Offenders will be held liable for payment of damages. All rights created by patent grant or registration of a utility model or design patent are reserved.

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	Document type				Document status			
INNOMOTICS	Technical data sheet				Released			
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